U-NET FOR PANCREAS SEGMENTATION IN ABDOMINAL CT SCANS

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ABSTRACT

In this paper, we propose a U-Net based approach for pancreas segmentation. Under the same setting where bounding boxes are provided, this method outperforms previously reported results with a mean Dice Coefficient of 86.70 for the NIH dataset with 4-fold cross validation. Results show that a network trained from scratch with medical images can achieve a better performance with much less training time compared to fine-tuning the models that are pretrained on natural images.

1. INTRODUCTION

The fixed-point model [1] which fine-tuned an ensemble of networks pretrained on natural images with three views of CT volumes achieved the best result so far on the NIH pancreas dataset [2] while obtaining $83.18 \pm 4.81\%$ Dice Coefficient (DSC) given the pancreas bounding boxes. Our study shows that a single network trained only on axial view slices can push this limit to $86.70 \pm 3.51\%$ with much less training time.

2. METHOD

2.1. Preprocessing

Slices are cropped with bounding boxes and added with margins filled with original image data as reported in [1]. The images are then clipped between [-100, 240] HU considering the common intensity distribution of pancreas, and scaled to the range [0, 1]. Only slices with at least 100 pancreas pixels are used for training.

2.2. Fully Convolutional Network

2.2.1. Network Architecture

The network is basically the same as the 2D U-Net [3] except that (1) all up-convolutions (upsampling + convolution) are replaced by transposed convolutions with size 2×2 and stride 2, and (2) the final layer is set to one feature channel with sigmoid as the activation function.

2.2.2. Dice Loss Function

We use the negative of a softly defined Dice Coefficient as the loss function during network training, similar to the one applied in [1]. The loss is defined as

$$L(Y, \hat{Y}) = -\frac{2\sum_{i} y_{i} \hat{y}_{i}}{\sum_{i} y_{i} + \sum_{i} \hat{y}_{i}}$$
(1)

where $y_i \in Y$, $\hat{y}_i \in \hat{Y}$, and Y is the ground truth, \hat{Y} is the prediction.

2.2.3. Training Settings

The network is trained from scratch with Adam optimizer and a learning rate of 10^{-5} for 10 epochs with batch size of one. The network is implemented with Keras with Tensorflow backend. It takes ~3 hours to train the network with one NVIDIA Tesla K40c GPU which is less than 1/3 time needed by the approach in [1].

3. EXPERIMENTS

3.1. Dataset and evaluation

We evaluate the proposed method on the NIH pancreas segmentation dataset [2] with 4-fold cross validation under exactly the same test setting with oracle bounding boxes as used in [1]. Performance is evaluated by Dice Coefficient.

3.2. Results

Table 1. Test Results Comparison		
Method	DSC (%)	Min DSC (%)
Fixed-Point [1]	83.18 ± 4.81	65.10
Proposed Method	86.70 <u>+</u> 3.51	73.67



Fig. 1. Sample segmentation result (Green, blue and red indicate prediction, ground-truth and overlapped regions)

4. CONCLUSION

An efficient segmentation approach is presented which surpasses previous results. Training with medical images from scratch is shown to be more effective than fine-tuning models pretrained on natural images. In the future, a detection system is to be built to incorporate this segmentation model.

5. REFERENCES

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